

## Development of pellet technologies for tokamaks and ICF

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### Introduction.

Present contribution is a result of activity of several scientific teams working in a tight collaboration to develop the following techniques and software for pellet injection [1]:

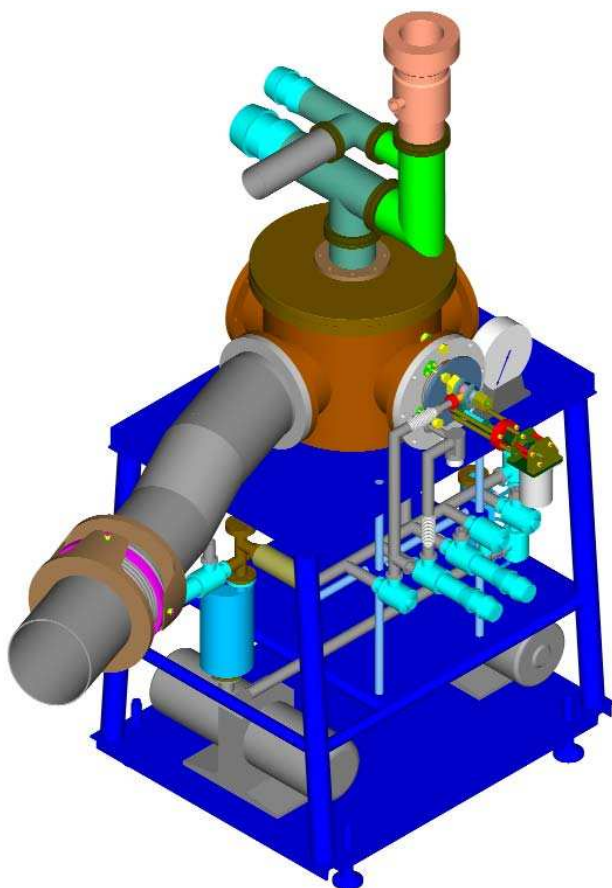


Fig.1. 3D drawing of ITV5.1 centrifuge pellet injector for Globus-M spherical tokamak.

- pellet guide systems with funnels and commutation units;
- modeling of pellet evaporation, cloud formation and evolution;
- modeling of transport processes after pellet injection, including formation of transport barriers;
- interface unit for centrifuge pellet injector providing a small angle of horizontal pellet spreading at the centrifuge output;
- injection of minipellets with small well reproduced velocities for plasma machine with low density or very short discharges;

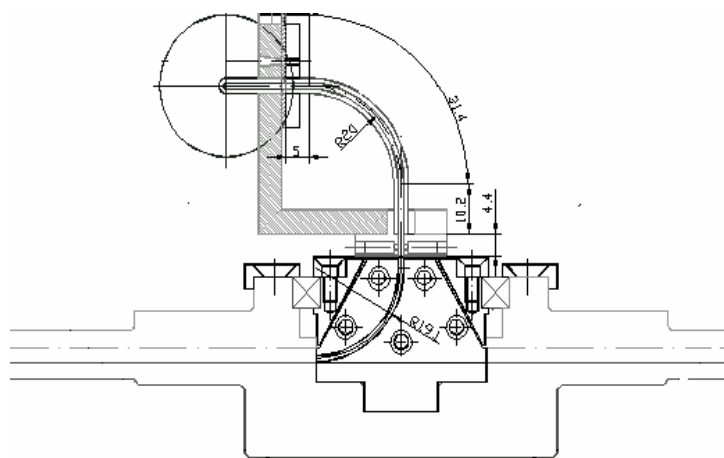
### Centrifuge pellet injectors.

TUAP Ltd., SPbSPU and Efremov Institute teams in collaboration with Globus-M team in Ioffe insitute

works on the further development of ITV5.1 centrifuge pellet injector for Globus-M



*Fig.2. Photo of the accelerating arm of ITV5.1 centrifuge pellet injector.*



*Fig.3. Drawing of interface unit of ITV5.2 centrifuge pellet injector. Rotating arm of the centrifuge has a curved part started from the rotation axis direction, this allows to avoid usage of a stop cylinder.*

the curved part placed exactly on the rotation axis. Pellets, which are initially accelerated mechanically or by gas up to 100 m/s, go through fixed tube to the input of rotating tube.

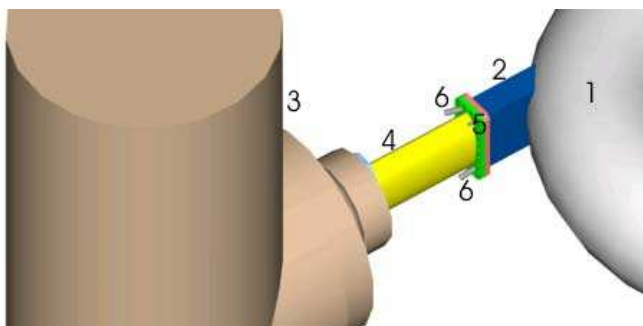
### **Pellet injector for plasma systems with short discharges.**

TUAP Ltd. and SPbSPU teams in collaboration with GOL3 team in Budker Institute works on the further development a gas-kinetic pellet injector ITV7 for GOL3 multiple-mirror machine in Budker Institute. This injector produces small solid hydrogen pellets (D1x1 mm) and injects them with a low velocity (10 - 100 m/s). Initial acceleration is mechanical (with pusher) and then low pressure gas produces final gas dynamical acceleration. The pellet is used as a target for a relativistic electron beam that creates plasma in GOL3. A strong requirement is reliable registration of pellet velocity and exact prediction

spherical tokamak operating in Ioffe Institute. This injector can test different types of the interface unit between a pellet formation unit and an acceleration arm of the centrifuge. ITER

relevant technical solutions will be tested on the centrifuge. 3D drawing of the centrifuge is presented in fig.1. Photo of the accelerating arm of ITV5.1 centrifuge pellet injector is shown on fig.2.

As an alternative to a stop-cylinder unit is a interface unit with curved tube which is shown on fig.3. Acceleration channel of the rotating arm is curved in vertical plane at the begin. Input of



*Fig.4. 3D drawing of combination pellet and NBI injection into a one port of TUMAN-3M tokamak. 1 – TUMAN-3M; 2 – tangential port; 3 – NBI injector; 4 – elliptical connection of NBI injector to the tangential port; 5 – tube for pellet guide system connection; 6 – additional small flanges for pellet diagnostics.*

a time when pellet will be on the axis of GOL3 machine to provide synchronization electron beam source and pellet injector.

### **Pellet and NBI injections.**

TUAP Ltd. and SPbSPU teams in collaboration with TUMAN-3M team in Ioffe institute are working on a connection both ITV4 pellet injector and NBI injector to the tangential port TUMAN-3M tokamak. ITV4 pellet injector is multibarrel in-situ solid hydrogen pellet injector. NBI injector placed near to the port and connected directly to it. ITV4 pellet injector is connected to the port by PGS2.2 pellet guide system with a differential pumping. Drawing of the port connection is shown on fig.4.

### **Modeling of pellet injection into TUMAN-3M tokamak.**

A new code for calculation of pellet ablation and plasma relaxation after pellet injection has been developed. The main motivation of the development this software was supplying pellet injection team with a tool which allows a fast calculation and analysis of current experiment during the interval between tokamak discharges. So in the code we prefer really measuring parameter instead of dimensionless values, real geometry of the tokamak and pellet injector, also we avoid time consumption iterations and fine meshes.

The code includes Parks scaling for pellet evaporation rate [2, 3]:

$$\frac{dN}{dt} = 1.08 \cdot 10^{16} n_e^{0.333} T_e^{1.64} r_p^{1.333} A_p^{-0.333}$$

Here N – number of atoms in the pellet,  $n_e$  and  $T_e$  – electron density and temperature of the plasma,  $r_p$  – pellet radius.

Depletion of plasma in case small volume of magnetic tube (center of plasma discharge) or long evaporation in the frame of the same tube (tangential injection) is taken into account according [4]:

$$Q_e^d = Q_e \frac{2\pi R r (V_{Pel})_r}{V_{Te} r_0^2} \left( 1 - e^{-V_{Te} r_0^2 / 2\pi R r (V_{Pel})_r} \right)$$

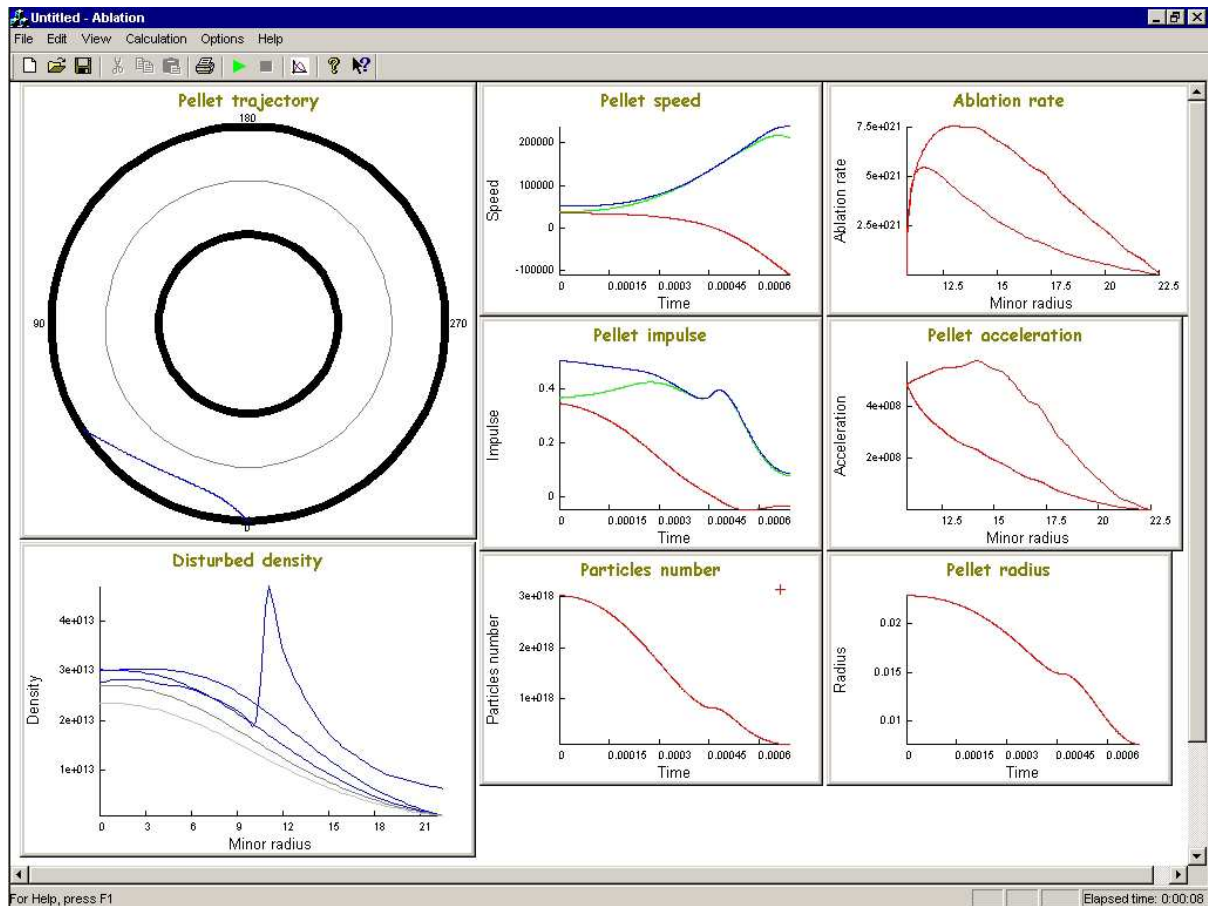


Fig.5. Output window of the code for calculation of pellet ablation and plasma relaxation after pellet injection.

Here  $Q_e$  and  $Q_e^d$  are electron fluxes on the pellet without and with depletion;  $(V_{pel})_r$  – radial projection of pellet velocity.

Pellet acceleration due to asymmetric of electron distribution function in plasma with current describes as in ref. [5]:

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### References.

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